W4IKS-2070

2070 Local Controller Software



DESCRIPTION

W4IKS is the most advanced, user friendly, and most widely used local controller firmware in the country. The IKS stands for "Includes the Kitchen Sink" and this firmware certainly lives up to it's name. W4IKS has now been adapted to the 2070L controller utilizing the OS9 operating system. And of course, the W4IKS-2070 will run W4IKS timings.

This versatile 2070 program uses terms and timing parameters found in NEMA programs with the addition of many important features not found in any other programs. A unique command box feature allows users to "customize" the program to accomplish things that no other program can.

The philosophy at Wapiti Micro Systems is to provide a software package that is versatile enough to meet any unique applications your intersection may require. This concept eliminates the need for single application software that will only work in limited locations, thus allowing the user to standardize on one software package that can be used anywhere! We designed the structure and operation of the program to meet the needs of the practicing Traffic Engineer and Signal Technician for now and in the future.

FEATURES

Enhanced 170 type FREE DISPLAY (*when used with 8 x 40 LCD display) Phase & Condition stay in view when entering data. Phase & Condition also shown in English. Keystrokes displayed on separate line.

For data entry—the data label is shown with its value.

Phases

- Rings
- Overlaps
- Pages
- Intervals
- (4) Limited service charts Walk Min.
- (8) Right turn overlag.
 Advance warnings
 Overlap delay time
 Operator set barriers
 Stracolls
 Flashing Dw
 EV Flashing DW
 Min.
 Max Min Initial (8) Right turn overlaps

- Restricted phases
- Conditional service
- Dual entry
- Left turn type

Per Phase

- Max & Max II
- Walk & Walk II
- Advance Walk
- Walk Delay
- Handicap Walk
- EV Flashing DW
- Passage

Per Phase - (continued)

- Min Gap
- TBR
- TTR
- ADD/Act
- Yellow
- All Red
- Red Revert
- Red Revert Min

Wapiti Micro Systems

FEATURES - (Continued)

Coordination:

- Operator set priority for plan implementation from: TOD plan, TOY plan, Modem plan, Hardwire plan, Command Box plan,
- Input plan, Bus plan, Manual plan.(32) Plans
- Dwell or Enhanced transition
- Earliest start point for each phase
- Allowable service time each phase
- Max service time each phase
- Split or force off settings
- Ped permissive per phase
- Permissive 1 & 2 per phase
- Offset—offset point
- Plan to run with set ped activation
- Coord max recall
- Coord min recall
- Coord ped recall

Pre-emption

- EV's
- RR's
- LRT's
- Bus

ΕV

- Delay
- All Red before EV
- All Red
- Min after call
- Min / Max
- Priority against other Pre-empts
- Hold priority
- Force priority
- Recovery method
- Min time before next call
- Early terminate phase
- Return phase(s)

Inputs/Outputs:

Each of the 64 inputs and 80 outputs has its own assignments (x5pages)

Outputs:

- Select output for pin from all available outputs (multiples allowed)
- Each output can be assigned for flashing.
- Each output can be assigned for dimming.

Inputs:

- 20 possible assignments for each input pin.
- Phase
- Extension and/or call
- Delay timing
- Carryover timing

Double clearance

• Clear phase(s)

Clear overlaps

Limited phase(s)

Limited overlaps

Return phases(s)

Priority against other pre-empts

Clear time 1

Clear time 2

Hold priority

Force priority

• Type 3

RR

Inputs (continued)

- Switching
- Ped
- Count
- Sample
- Fail on time
- Fail off time
- Length bin assignment
- Speed loop A or B
- Length
- Occupancy
- Options 1-4

Options = EV, RR, LRT, Bus, Ped inhibit, Adv Enable, Advance, Flash Sense, Stop Time, Flash, Hold, Force, Time Transfer, Max II, Free, Cycle, Split, Offset, Coord Plans 1-18, Special Functions, Command Box, Overlap Ped, Handicap Ped.

LRT

Clearance phase(s) Limited phases Limited overlaps Return phases Delay Time to Green for LRT Allow move to return phase if time allows Min / Max Limited wait Flash go light Recovery method

Command Box

Hold priority Force priority (16) latches (16) timers (6,499.9 seconds) Box size—5000 entries 201-219 commands

Traffic Management Software

W4IKS-2070 firmware has been designed to operate with W7OSM-2070, an on-street master program also developed by Wapiti Micro Systems. Both have been developed to communicate with TrafficView32, a Closed Loop Traffic Management System. The purpose is to create a powerful system that allows a Traffic Engineer to fully control & maintain all of his intersections right from his desktop.

HARDWARE

W4IKS will operate on 170 controllers with Motorola 6800 processors & HC11 processors. A version of W4IKS is also available to work with the 2070L controller, Intelight's SmartCard Processor, SBC Controller, and McCain's Coldfire Controller.

Wapiti has also developed a new GPS time update for ultra accurate time.

PH# (440) 975-1167 Email: sales@wapitimicrosystems.com

Invert input call Bus Bus plans

- Delay
- Frequency
- Priority